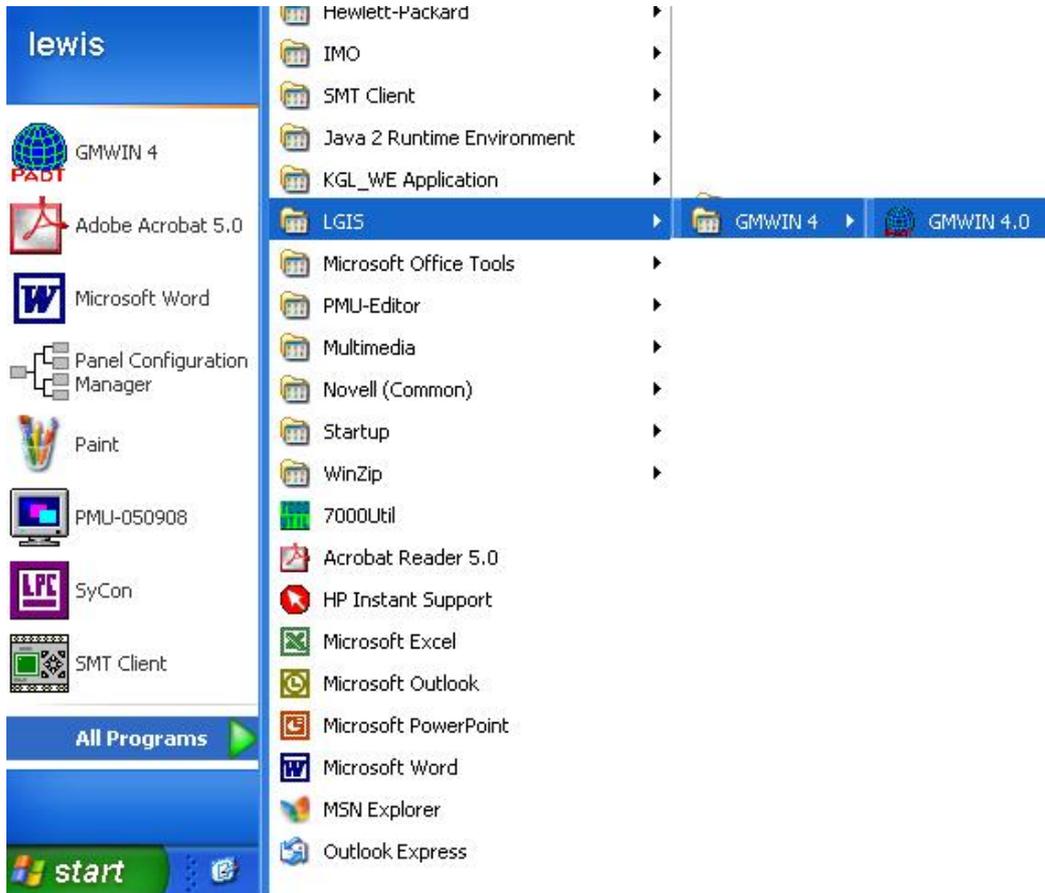


GMWin Project

$\mu\mu$

GMWin.

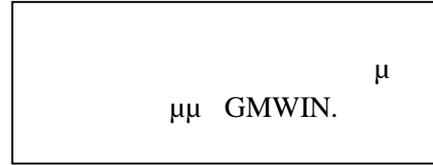


3

$\mu\mu$ GMWIN



4



μμ

GMWin μ

GMWIN

μμ
μ

μ

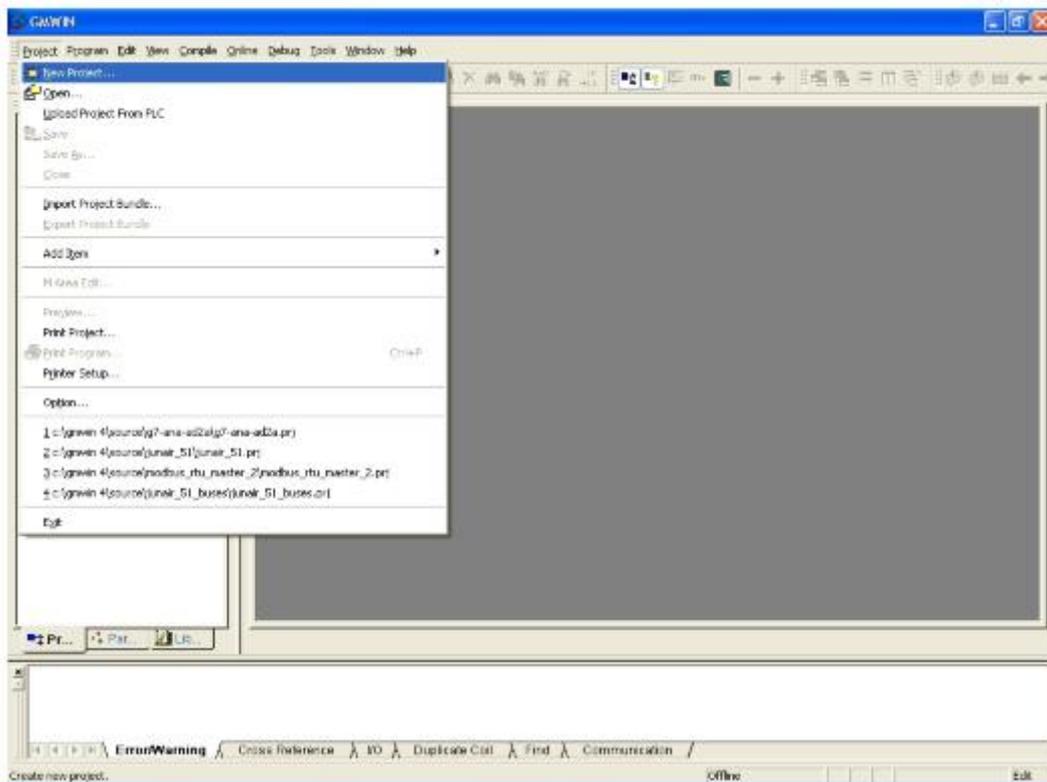
,

New project»
μμ

μμ ,
«Project»

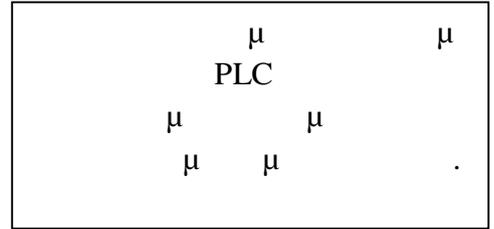
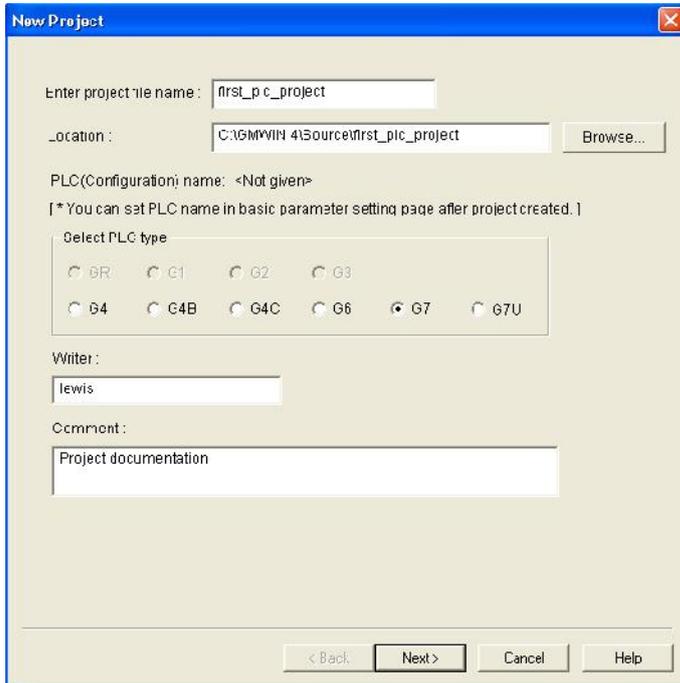
«

μ
«New Project».



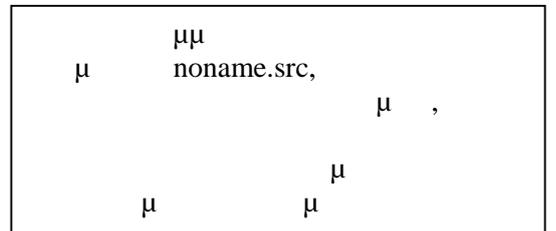
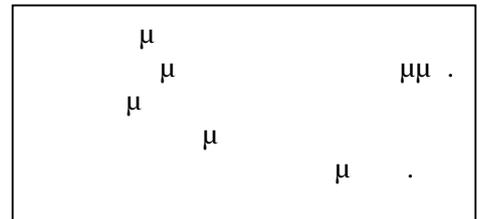
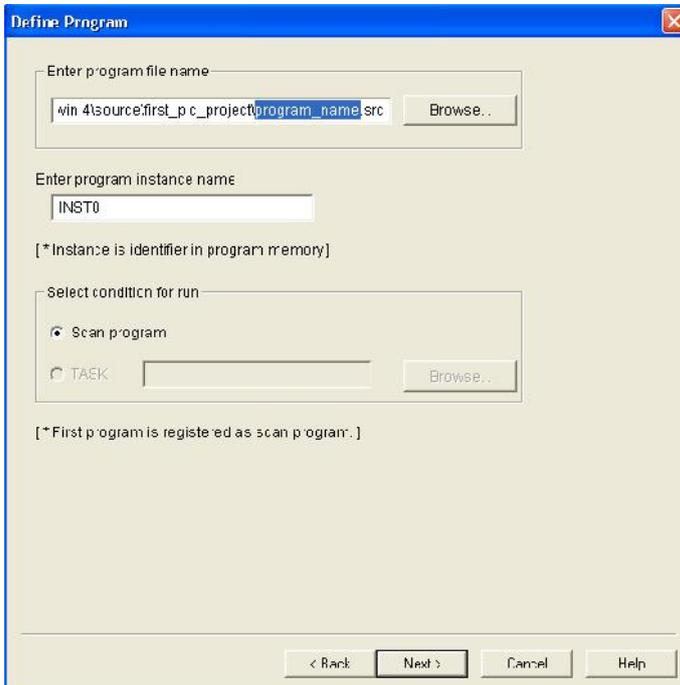
5

μ μ
μμ



6

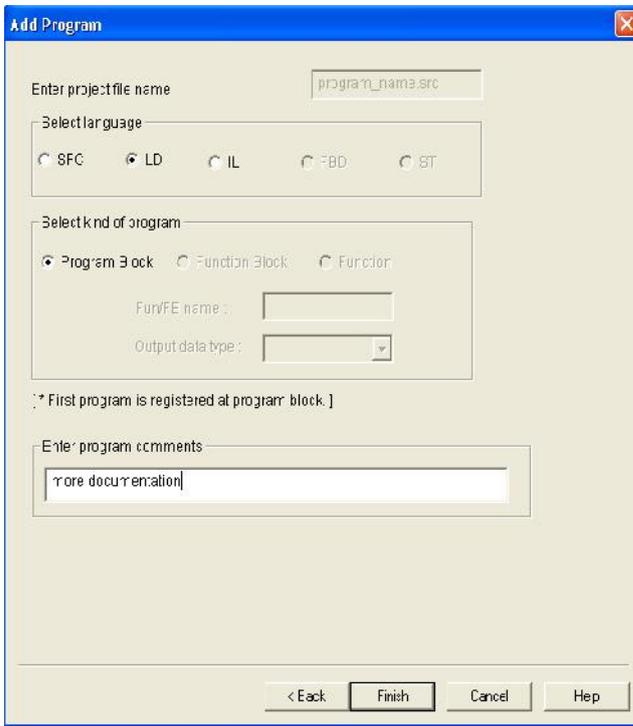
PLC



7

μ

μμ



μ μ
μ
μ μ .
LADDER. μ

SFC, LD IL
μ

μ . μ μ

8

μ μ

[Finish]

μ

μ

μ μ μ .

μ

μ μ GMWin

To

μ μ μ
μ μ μ

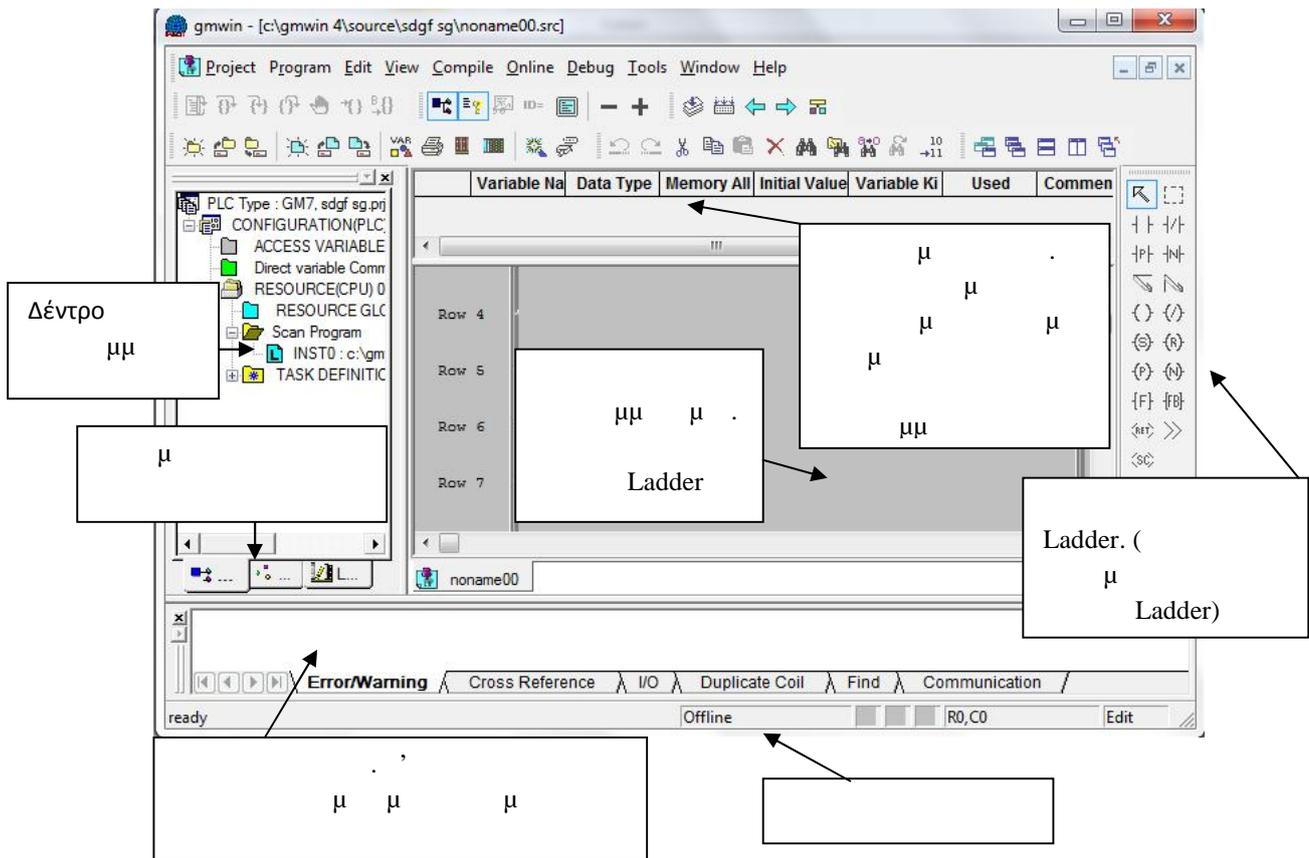
GMWin
«windows»

μ μ
μ

μ μ μ
, μ μ

μ μ .
μ μ .

μ



9

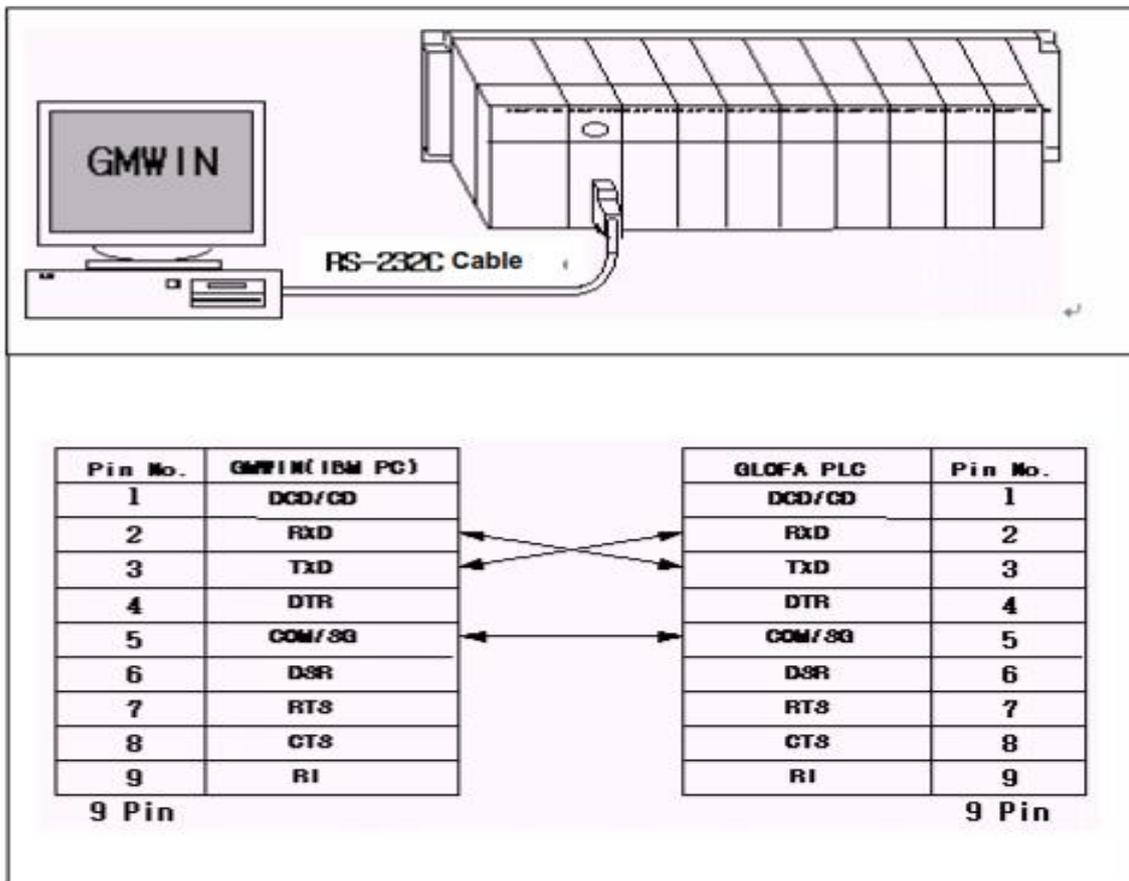
μ PLC
 μ GMWIN μ PLC μ 2 -
 μ 5 : μ RS-232C, μ modem,
 μ (Ethernet), μ USB μ 3 :
 μ 1 2.
 μ [Project]-[Option].

μ

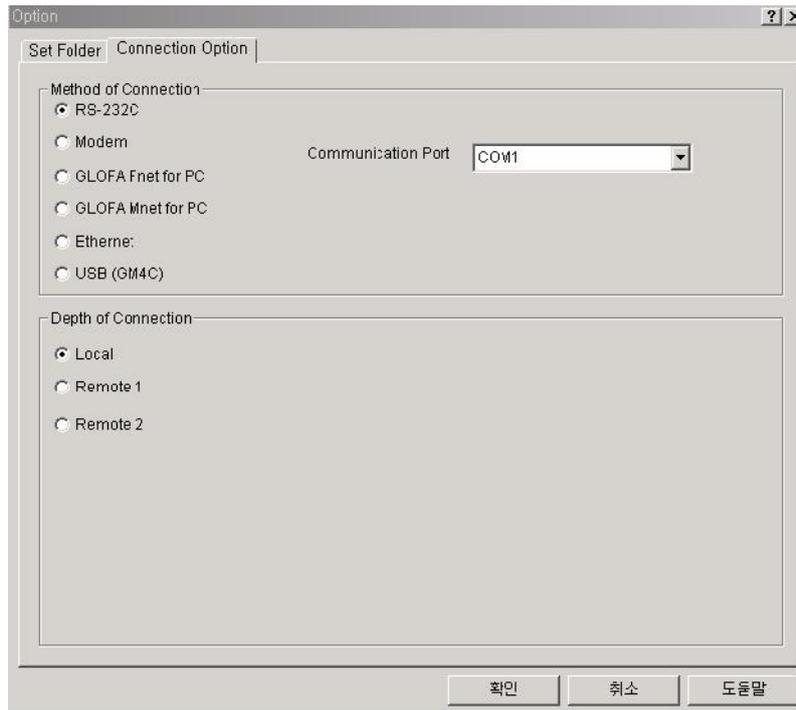
- 1) μ Project μ Option.
 μ Connection Option.
 : i) Number of retry: 1, ii) Method of Connection: RS-232C, iii) Communication port: COM1 COM2 (μ μ μ), iv) Depth of Connection: Local
- 2) μ PLC μ
 PAU/REM (μ).
- 3) μ Online μ Connect.
- 4) Online, μ PLC mode μ
 RUN.
- 5) μ μ μ 'Would you like to change to the Run Mode' μ
 Yes.

- 6) Online Write.
 7) ('Parameters and Program – Upload Program')
 OK.
 8) 'To write to PLC, PLC must be at stop mode. Switch PLC to stop mode?'

RS-232C RS-232C PLC
 RS-232C, 3, 9
 (KIC-50A).
 D



- [Project]-[Option].
- [Connection Option].

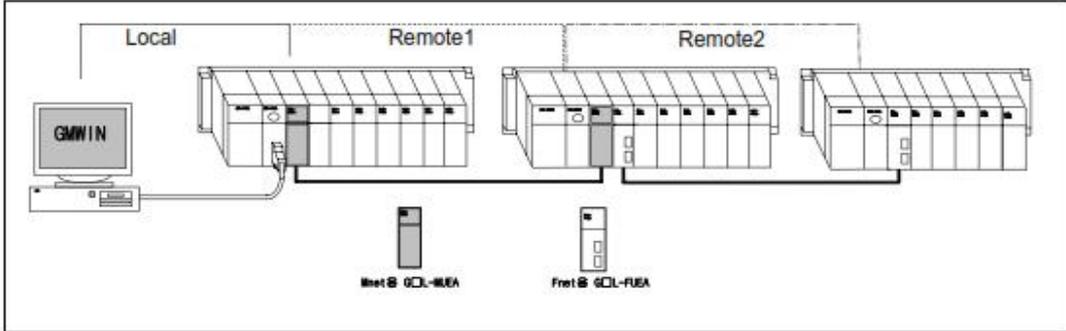


11

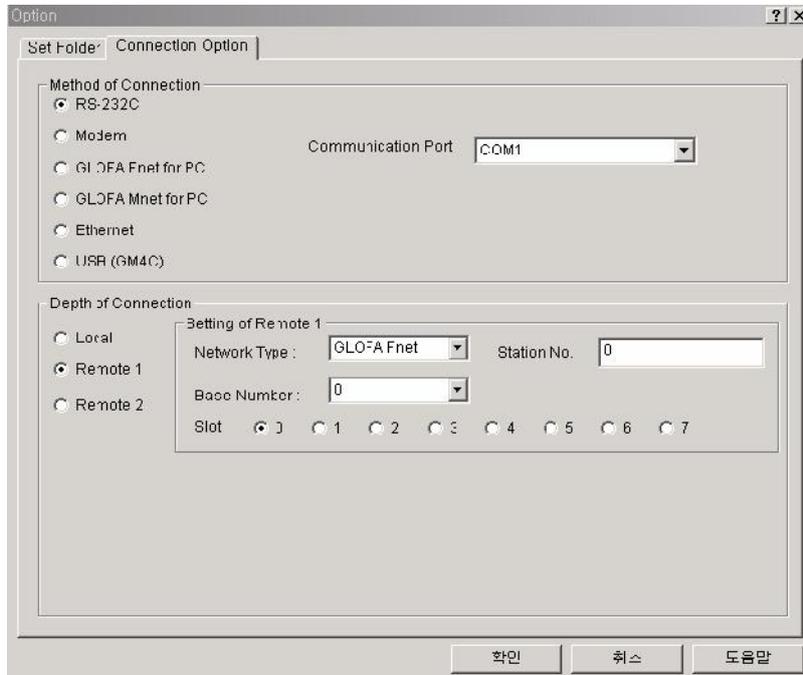
- μ 'RS-232C' μ .
- μ 'COM1~COM4' .
- μ 'Local' [OK].
- μ [Online]-[Connect], RS-232C
- μ PLC .

- | | | | |
|-------------|---|----------|-------|
| 1. | μ | μ | μ |
| 2. | μ | μμ . | COM1 |
| GMWIN V4.0. | | μ | COM1, |
| 3. | | RS-232C, | μ |

μ RS-232C μ RS-232C
 PLC
 μ μ μ μ PLC

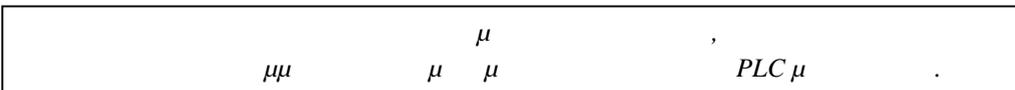


12



13

- RS-232C
- COM1~COM4
- Remote 1 and Remote 2
- μ μ , μ μ μ
- μ μ μ μ μ μ
- [OK]. μ [Online-Connection], PLC



μ

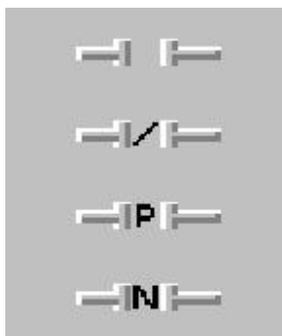
1

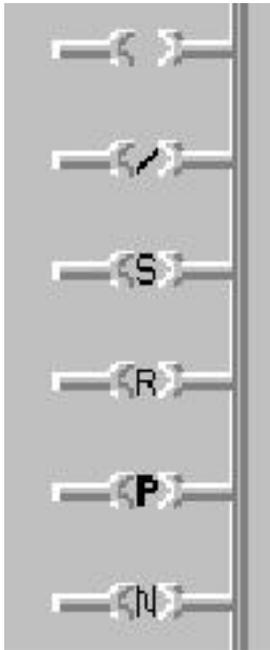
1

Σύμβολο	Κλειδί συντόμευσης	
	F2	
	F3	
	F4	μμ
	F5	μμ
	F6	
	F7	
	F8	
	F9	
	Shift+F1	
	Shift+F2	
	Shift+F3	
	Shift+F4	
	Shift+F5	
	Shift+F6	
	Shift+F7	
	Shift+F8	μμ
	Shift+F9	

μ

μ



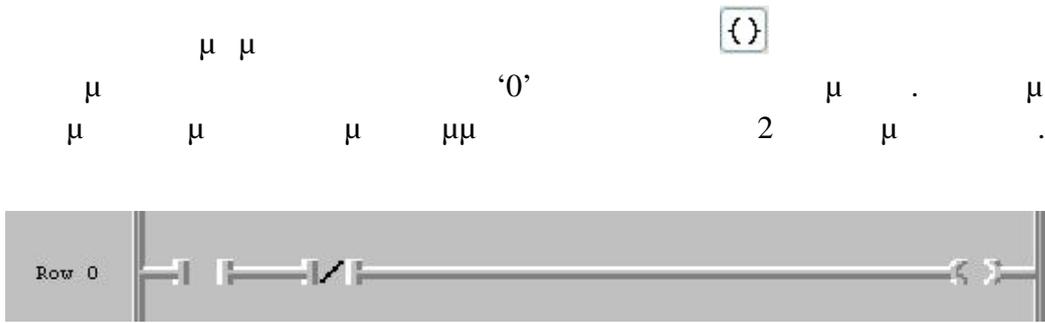


μ μ $\mu\mu$ **Ladder**
 μ OR μ μ Ladder μ μ μ AND
 μ GMWin μ μ Project.
 μ μ (NO) μ  '0'  '1'
 Ladder.



μ μ (NC) μ  '0'  '2'
 Ladder.





μ μ (NO) μ '1' '1'

Ladder.

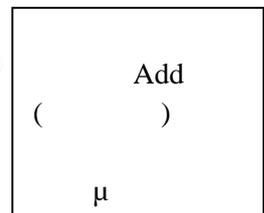
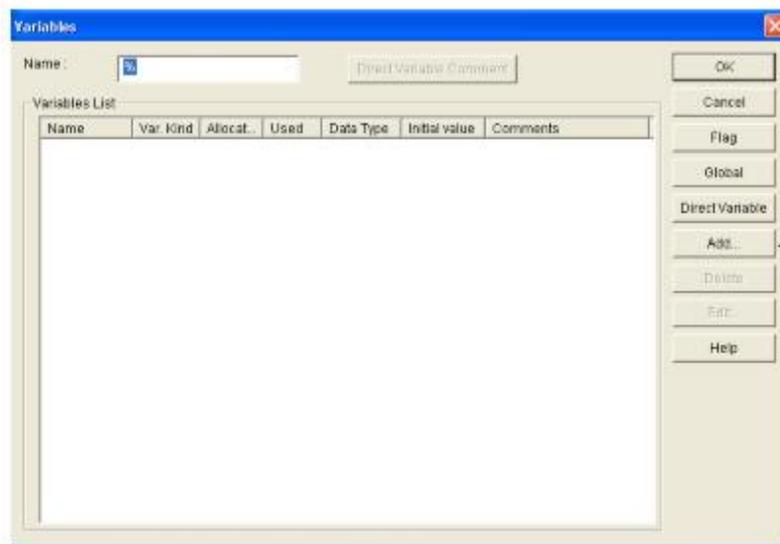


μ μ μ μ μ μ '1' '0'

Ladder.



μ μ μ μ μ μ μ μ μ



15 μ

Add/Edit Variables

Variable:

Variable Kind:

Data Type:

 Elementary:

 FB Instance:

 Array (0..) OF

Memory Allocation:

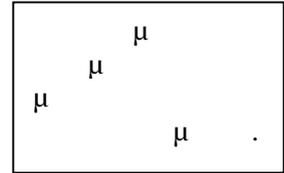
 Auto

 Assign(AT):

 %

Initial Value:

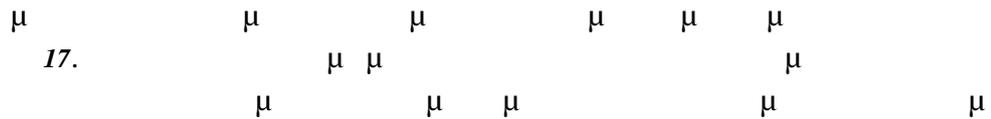
Comments:



16 μ μ

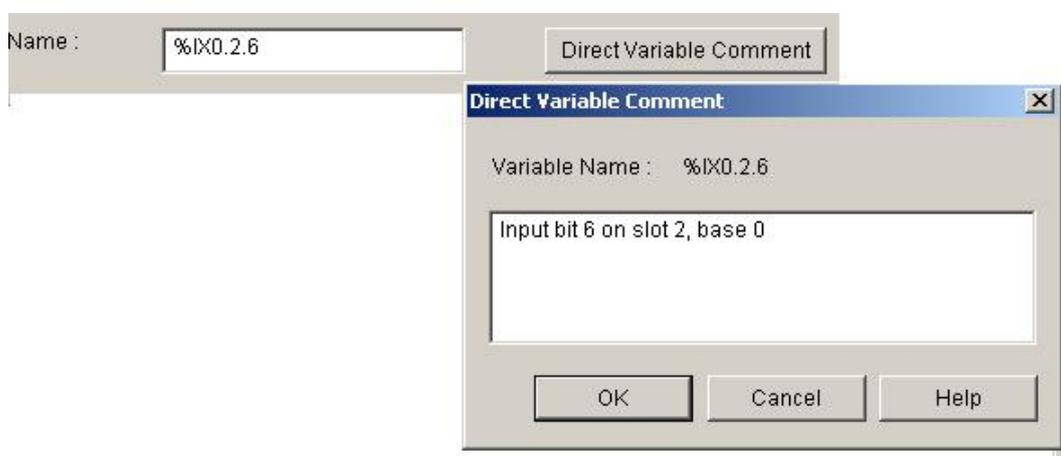
2 μ μ

Name	Type	Address	Comment
Enable	BOOL	%IX0.0.0	1 st input to enable
Reset	BOOL	%IX0.0.1	2 nd input to reset
Motor	BOOL	%QX0.0.0	Motor on 1 st output



OK.

Ladder.
 H
 %
 (X, B, W, D, L)
 , M,
 (I, Q, M),
 (I Q,), bit



19

% I X 0 . 2 . 6 : Input, Bit size, Base 0, Slot 2, Bit 6.
 % M W 32 . 7 : Memory, Word size, word 32, bit 7.

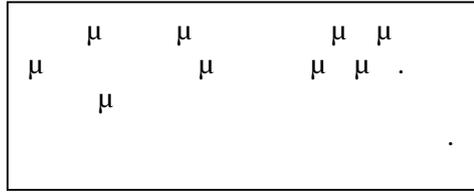
.

Memory Allocation

Auto

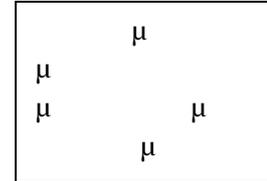
Assign(AT) :

%



23 μ μ

Initial Value



24 μ μ

Comments



25

μμ μ

Ladder

μμ μ , μ

Ladder. μ
μμ μ

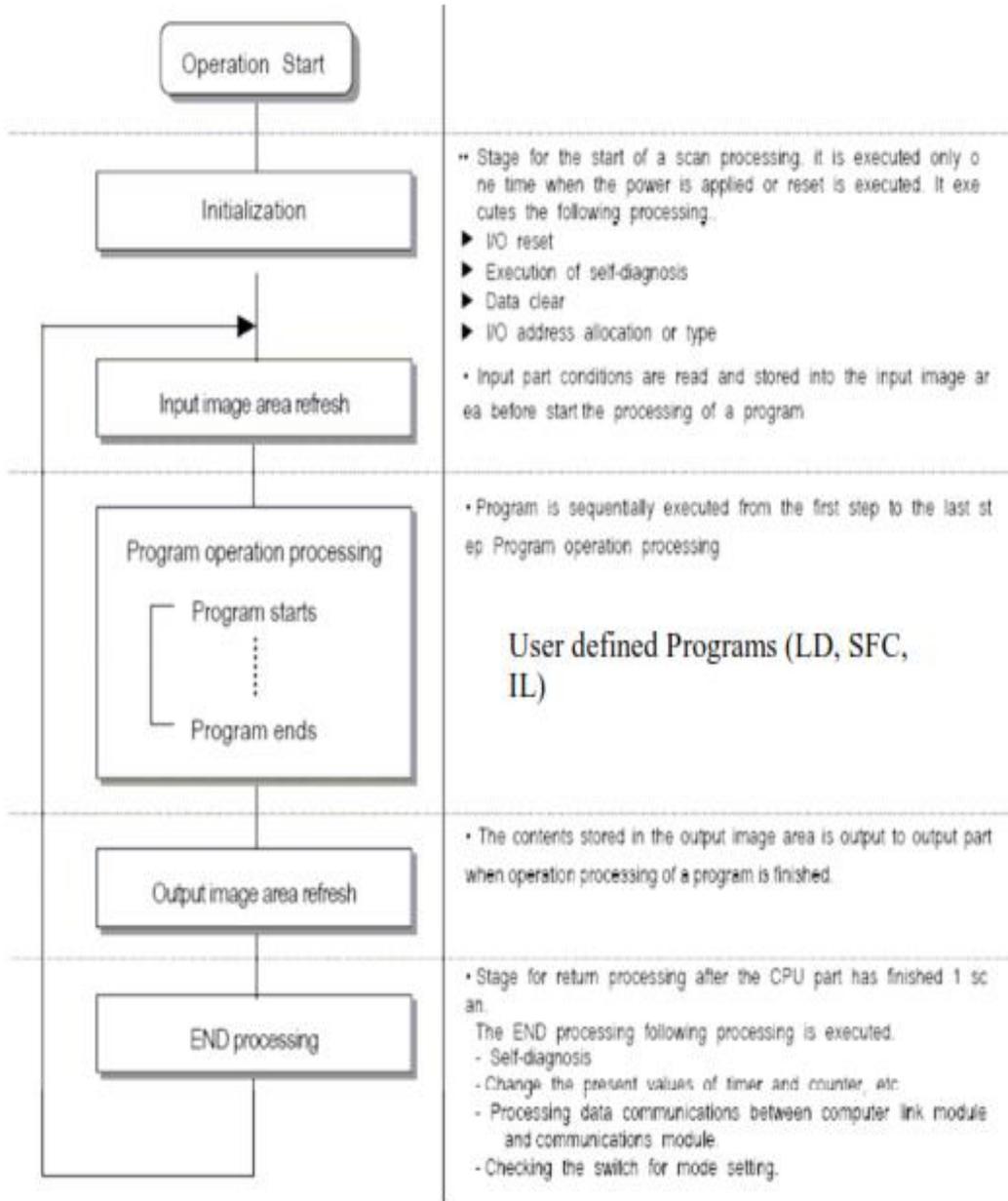
Ladder.

μ

PLC.

PLC.
GMWin project :

1. μ , μ
2. .
3. μμ
4. μ μ ,
5. μ μ μ .



μ 26

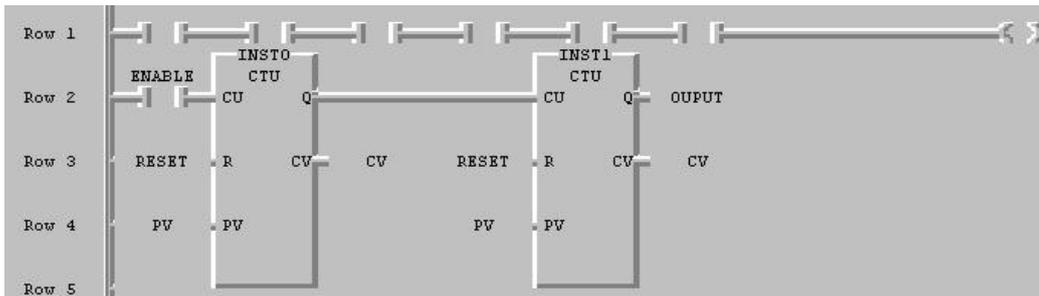
μ

!

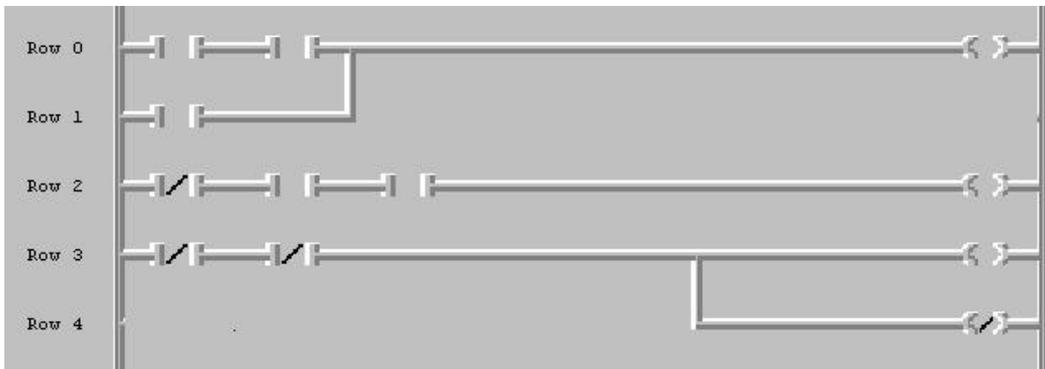
μμ

μ

μμ GMWin μ
 2. μ 1 μ
 μ μ
 30 μ μ μ μ
 μ μ μ μ μ μ
 μ μ μ μ μ μ

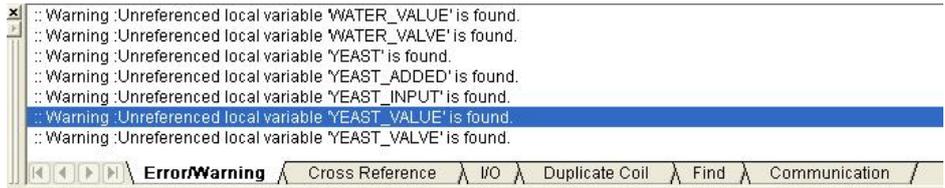


μμ μ GMWin / μ
 μ μ μ μ μ
 μμ μ μ μ



μμ μ μ
 μμ μ μ μ
 μμ μ μ μ (compile)

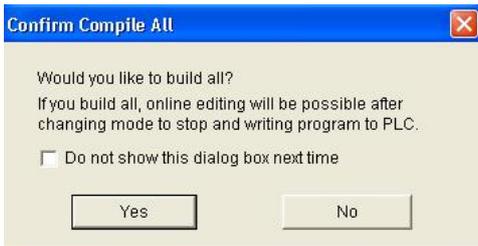
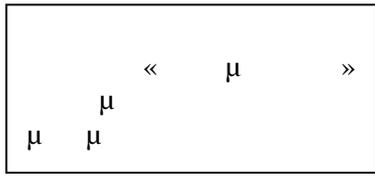




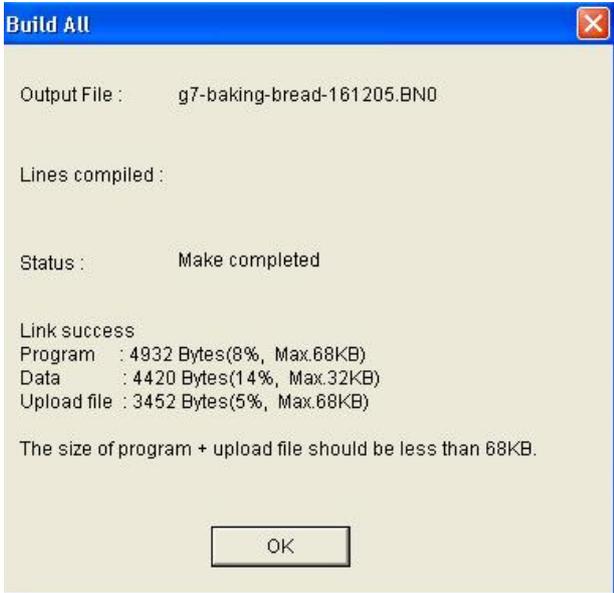
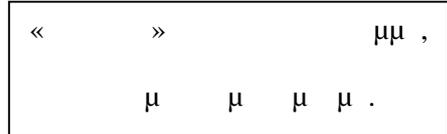
29

μ

μ μ μ (compile), μ μ μ Compile.



30 Build All (μ)



31 μ Build All

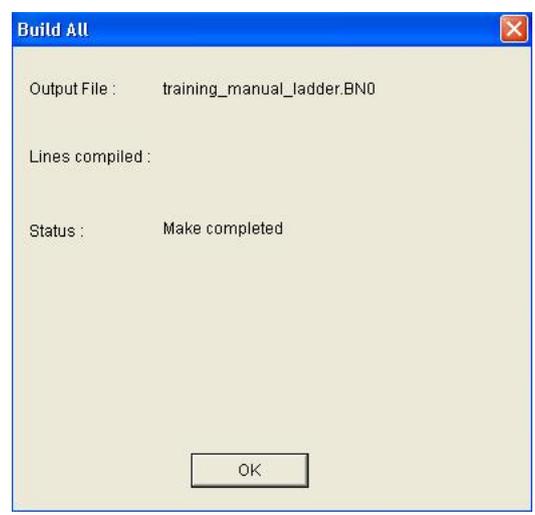
μ μ
 GMWin μ μ PLC.
 μ rack μ G PLC, μ μ μ PLC

μ
 «Start simulator» μ . (Tools)



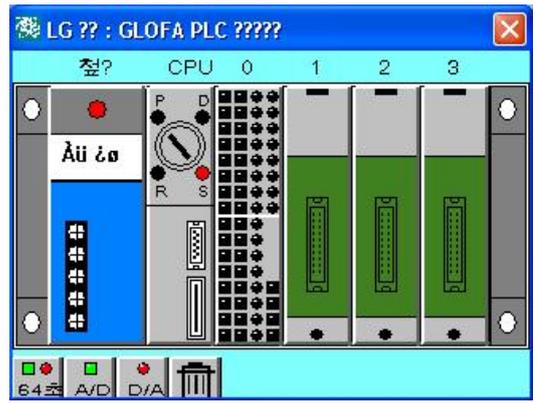
32 μ

μ μ μ , μμ « μ ».



33 μ Build All (μ)

μ PLC μ μ
 G4 G6 PLC. μ μ
 μμ G4 G6 μ μ
 μ I/O (/)
 μμ G7 μμ . 60 I/O
 (/) μ
 μ .

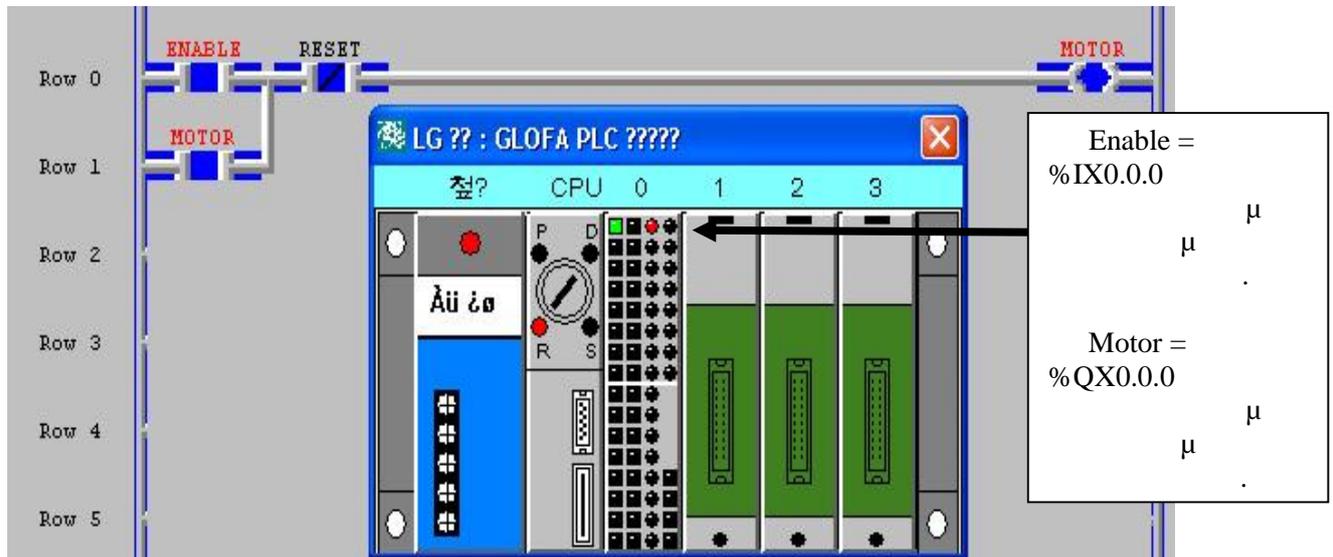


. . %IX0.0 = slot 0
 %QX0.2.3 = slot 2

34 ,

PLC

μ . μ μ

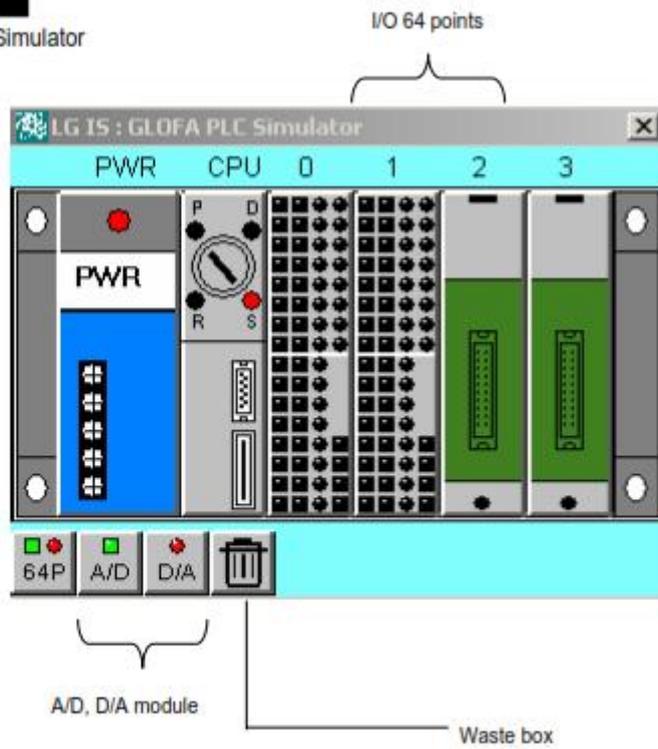


37

μ μ μ μ μ μ

Point

- GM7 Simulator



38 μ

GM7	μ	μ	μ	μ
/	μ	μ	μ	μ
38.	μ	μ	μ	64

CPU

